

# How to define the beam-plate interaction?

## 1. What does an eccentricity do?

The purpose of eccentricities is to have the behaviour of a calculation model (= Diamonds model) correspond as closely as possible with the real behaviour of the structure. The purpose of eccentricities is NOT to give the calculation model the same appearance as the architectural model.

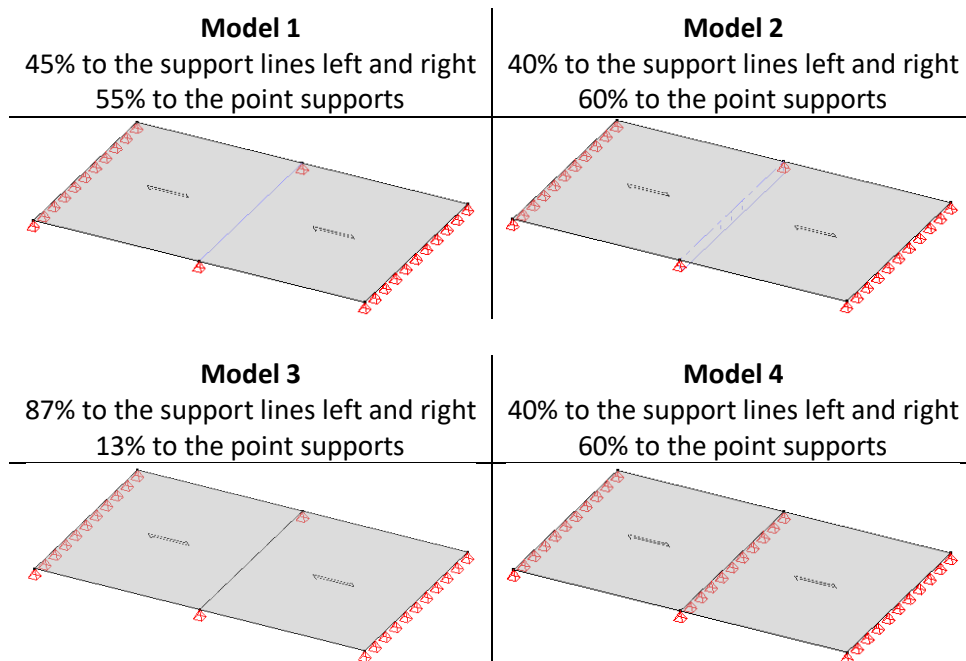
Eccentricities affect how the stiffness of the elements (plate and beam) are assembled:

- When the beam has no eccentricity (see Model 1 below): the rigidity of the plate will locally be increased with the rigidity of the beam (= the sum of both rigidities).
- When the beam has an eccentricity (see Model 2 below): the beam and plate will work together as a T-section. The rigidity of this composed section will be higher than the sum of both rigidities.

In order to illustrate this, we compare the load distribution towards the end support lines and the centreline in 4 beam-plate models<sup>1</sup>.

- Model 1: a beam in the middle, not eccentric
- Model 2: same beam in the middle, eccentric
- Model 3: no beam in the middle (or a beam with a very low stiffness in comparison to the plate)
- Model 4: a support line in the middle. The plates will behave as perfectly continuous.

Result:



<sup>1</sup> 9 x 5.5m, 1R slab of 0.2m thick, simply supported on two opposite sides, 10kN/m<sup>2</sup>  
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Conclusion:

- As expected, the beam in Model 2 acts stiffer than the one in Model 1. The beam in Model 2 draws more force to itself, then the beam in Model 1.
- With increasing beam stiffness, Models 1 and 2 will behave like Model 4.  
With decreasing beam stiffness, Models 1 and 2 will behave like Model 3.
- The percentages may vary depending on the length/width ratio of the plates and the plate type (one way slab, two way slab, prelabs, ...).

## 2. Eccentricities result in axial force

When we place a beam eccentric in relation to a plate, the beam axis shifts with respect to the axial plane of the plate. This creates a completely different force distribution:

- When the beam is not eccentric in relation to the plate, both are working in bending. There's not axial force in the system.
- When the beam is eccentric in relation to the plate, both bending and axial force will arise. If the beam is under the plate, there (usually) will be compression in the plate and traction in beam. If the beam is above the plate, there (usually) will be traction in the plate and compression in the beam.

Although the force distribution is different in both systems (with or without eccentricities), the total amount of bending moment remains the same. To illustrate this, we model a T-section in 3 different ways: §2.1 describes the geometry and the loads of the different models and §Fout! Verwijzingsbron niet gevonden. compares the internal forces. In §3.2.4.1 we come back to these model again regarding the reinforcement and cracked deformation.

### 2.1. Geometry + loads

	Way 1	Way 2	Way 3
Cross-section beam	T cross-section with dimensions: B=200mm H=700mm bf=1000mm hf=200mm	R cross-section with dimensions: B=200mm H=500mm	R cross-section with dimensions: B=200mm H=700mm
Cross-section plate	none	B=1000mm	H=200mm
Eccentricity $e$	none	Upper side beam = lower side plate $e=0,35m$	Upper side beam = upper side plate $e=0,25m$
Dead load	25kN/m <sup>2</sup> , which comes to a line load of 25kN/m for Way 1 (T-beam is 1m wide).		
	<p>The image shows three 3D perspective views of a T-section beam and its supporting plate.   <b>way 1:</b> A blue T-section beam is centered on a grey rectangular plate.   <b>way 2:</b> The blue T-section beam is positioned lower on the grey plate, creating an eccentricity.   <b>way 3:</b> The blue T-section beam is positioned higher on the grey plate, also creating an eccentricity.   Red arrows and labels indicate the beam and plate for each model.</p>		

### 2.2. Comparison internal forces

We look at the internal forces in the load group 'dead loads' (not ULS FC) because Way 3 contains a little more self-weight than the other two.

	Way 1	Way 2	Way 3
Bending moment $M_y$ in the beam			
Mean bending moment $M_{xx}$ in the middle of the plate			
Axial force $N$ in the beam			
Mean axial force $N_{xx}$ in the middle of the plate			
Total bending moment = $M_y + M_{xx} + N_{xx} \cdot e$	200kNm	38,7kNm+12,2kNm+426,8kN*0,35m =199,9kNm	99,9kNm+11,5kN+345,4kN*0,35m =199,9kNm

Conclusion: the total amount of bending moment in the system is the same. It's only being distributed in a different way.

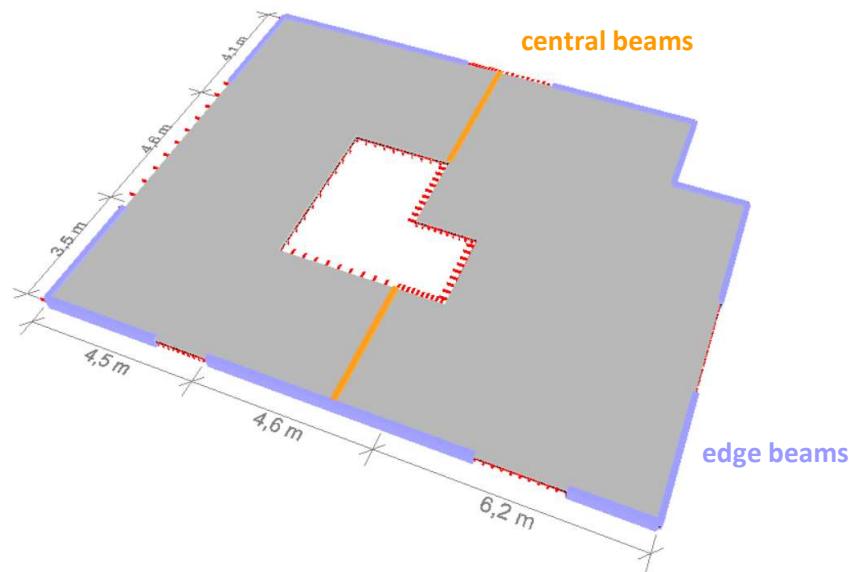
### 3. Collaboration concrete beam – concrete plate

#### 3.1. Aim

Consider the 2D plate model below (pre-slabs 200/50, beams R150/350, 15kN/m<sup>2</sup>). The beam-plate connections can be made in various ways on site:

- continuous plate, simply placed on the beam
- discontinuous plate, simply placed on the beam
- beam and plate are poured together. Both beam and plate will work together as a whole.

This implementation determines the modelling in Diamonds, because the modelling must describe the real behaviour of the structure as well as possible.



## 3.2. In Diamonds

This section looks at how the different ways of execution are modelled in Diamonds: with and without eccentricities. Working with or without eccentricities has advantages and disadvantages. You will notice that one situation lends itself better to the use of eccentricities than another.

### 3.2.1. Continuous versus discontinuous

Before getting started with the different cases, we'd like to illustrate the difference between a 'continuous' and a 'discontinuous' plate.

- In a 'continuous' plate, the reinforcements extends over different plate surfaces.  
In other words, all internal forces can be transferred between the different plate surfaces.
- In a 'discontinuous' plate, the reinforcements does not extend over different plate surfaces.  
In other words, no internal forces can be transferred between the different plate surfaces.

This continuous or discontinuous behaviour cannot be detached from the geometry/loads on the plate. Diamonds calculates the reinforcement based on the internal forces in the element. And the internal forces follow from the geometry (the boundary conditions!) and the loads.

On a discontinuous slab, there are hinge lines on the slab edges. These hinge lines prevent moment from being transferred between the different plate surfaces. These hinge lines therefore apply to both the top and bottom reinforcement.

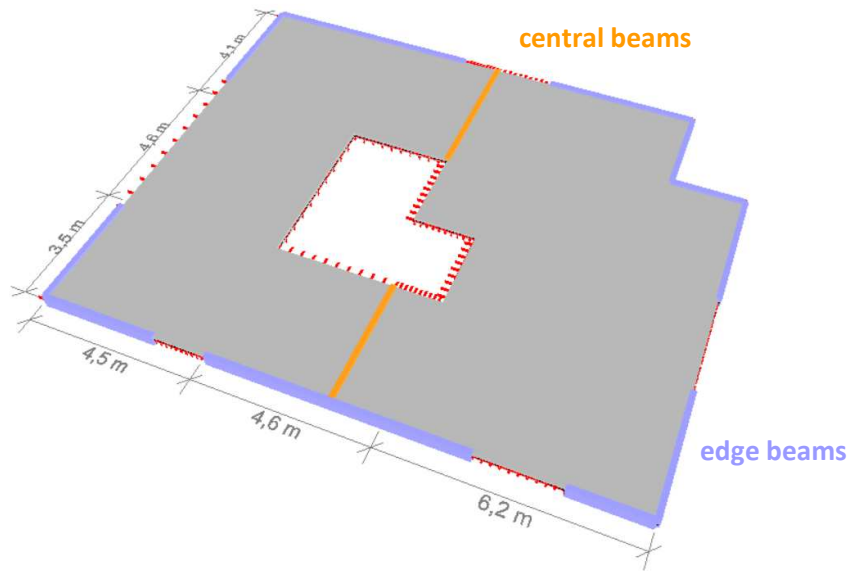
On a continuous slab, there are no hinge lines on the slab edges. All force action can be transferred.

Within Diamonds, the precondition 'continuous upper reinforcement and discontinuous lower reinforcement' (or visa versa) does not exist. There is only 'continuous upper and lower reinforcement' or 'discontinuous upper and lower reinforcement'.



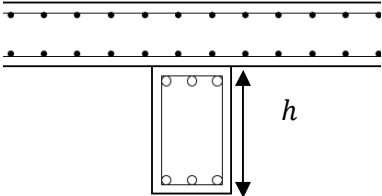
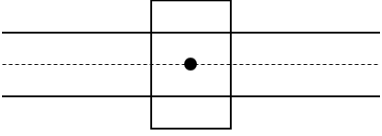
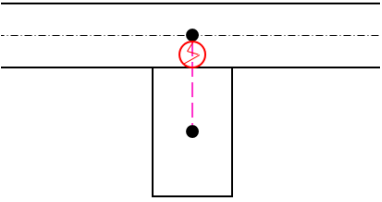








If it follows from the reinforcement calculation that at a slab edge: continuous upper reinforcement, discontinuous lower reinforcement, then this is a consequence of the loads on the slab. Not the result of a boundary condition that were applied, because there are no special boundary conditions that can force that behaviour.

### 3.2.2. Case 1: continuous plate, simply supported on beam

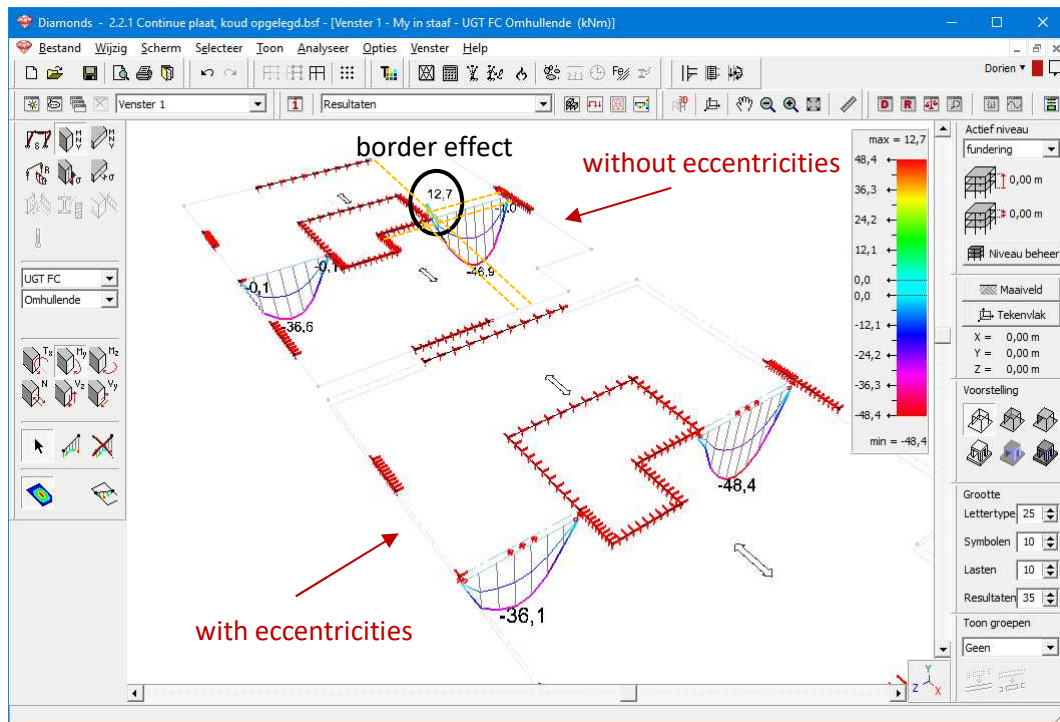
The plates in the 2D plate model are designed as discontinuous, simply supported by the central beams. For the support of the plates on the edge beams, see case 2.



The table below lists the assumptions made for each model.

REALITY	DIAMONDS	
	WITHOUT ECCENTRICITIES	WITH ECCENTRICITIES
	 License 2D slabs required	 License 2D slabs + 2D plates required
Case 1: Continuous plate, simply supported on beam 		
Note: this configuration makes only sense for a beam BETWEEN 2 plates! Not for a beam at the edge of a plate.	 -	 <ul style="list-style-type: none"> <li>• Top beam = bottom plate</li> <li>• Allow only transfer of N in rigid links.</li> </ul>
	 Beam height = h	 Beam height = h
	 Not possible to specifically turn off the moment transfer from the plates to the beam.	 Disable moment transfer on bar ends if you want simply supported behaviour.
	 <ul style="list-style-type: none"> <li>• Easy modelling</li> <li>• Bending moment can still be transferred from the plates to the beam → °torsion in the beams. Setting the torsional stiffness <math>I_t</math> of the beams to a small value, will eliminate the torsion, but with the risk of large (angular) deformation.</li> </ul>	 Complex modelling
	Reinforcement in plates and beam should be placed.	Reinforcement in plates and beam should be placed.

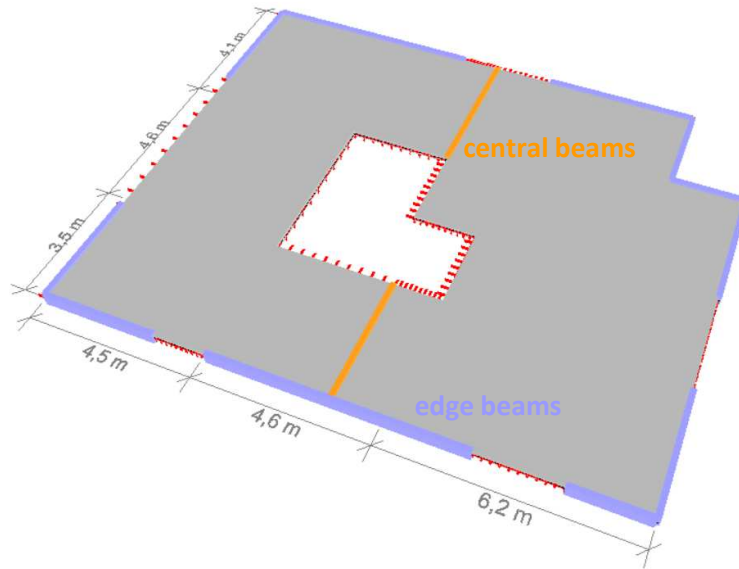
Result:





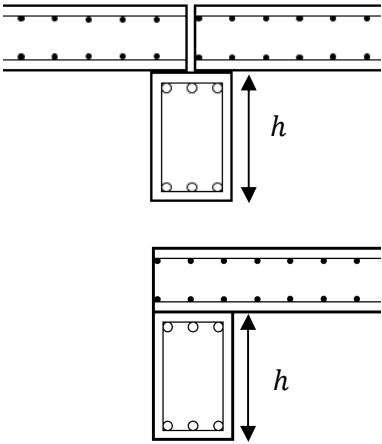
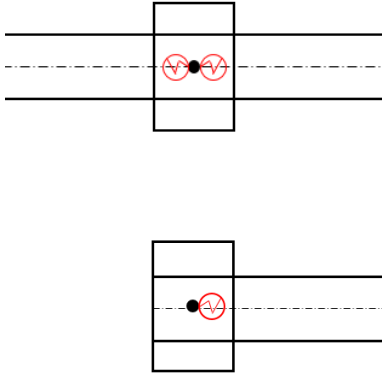
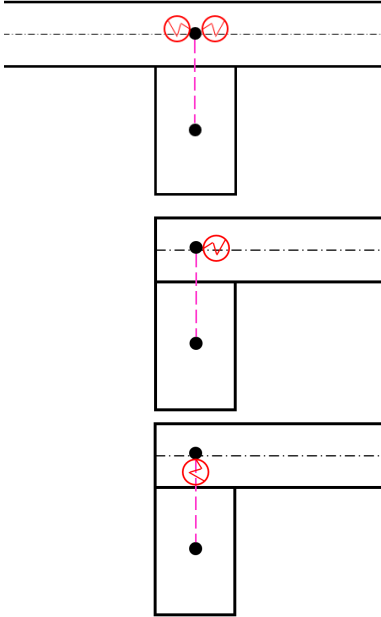










- The bending moment in the field is indeed comparable.
- Against all expectations, a retaining moment occurs in the model without eccentricities. This moment occurs because the plates can still transfer forces to the beam on one hand, and because of the compatibility of deformations on the other hand. With the compatibility of deformations means the following: the plate bears in two directions, so it also deforms in two directions. And because of a border effect. The deformation that the plate undergoes along the four orange cut lines, must remain compatible. And this is not always that easy, resulting in 'abnormalities' in the internal forces. 'Abnormalities' is between quotation marks, because the border effects are something you don't expect, but they are normal in this type of modelling. The only approach where they can be eliminated, is 1D modelling and simple load descent like in hand calculations. But hand calculations make a lot of simplifications, in a way that they are sometimes not comparable to the reality.

### 3.2.3. Case 2: discontinuous plate, simply supported on beam

The plates in the 2D plate model are designed as discontinuous, simply supported by the **central** beams. The plates in the 2D plate model are designed as simply supported by the central beams by the **edge** beams.



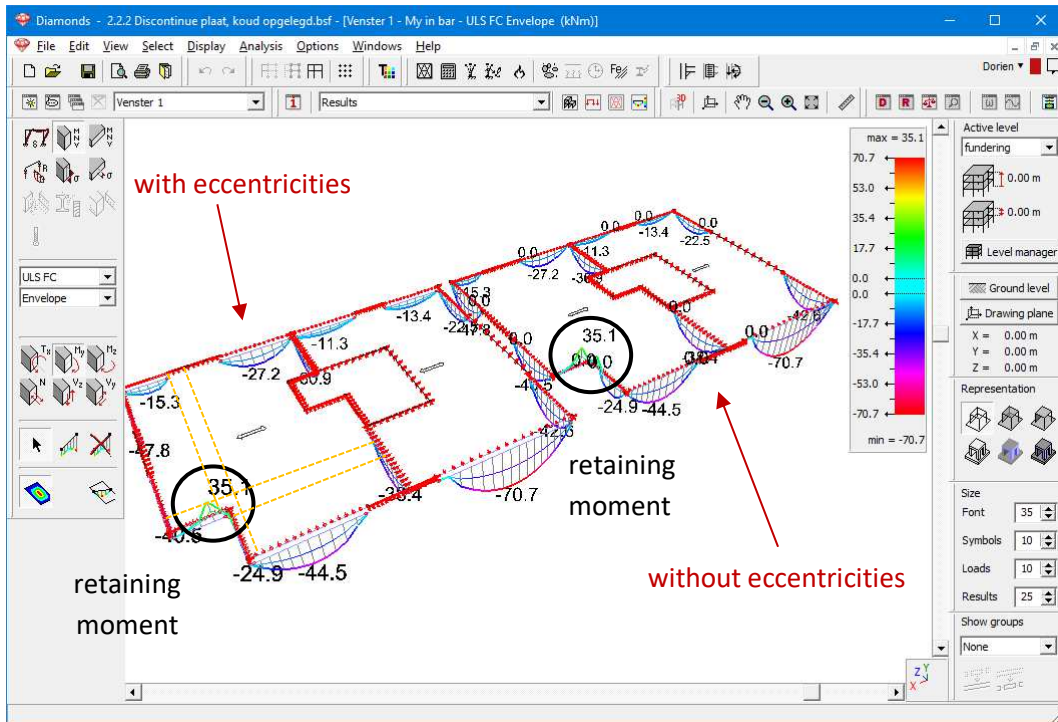
The table below lists the assumptions made for each model.

REALITY	DIAMONDS	
	WITHOUT ECCENTRICITIES	WITH ECCENTRICITIES
	 License 2D slabs required	 License 2D slabs + 2D plates required
Case 2: Discontinuous plates, simply supported on beam 		
		 <ul style="list-style-type: none"> <li>• Top beam = bottom plate</li> <li>• Option 1: allow only transfer of N in rigid links.</li> </ul>
	 Beam height = h	 Beam height = h
	 Allow only transfer of V along the plate edges	 Allow only transfer of V along the plate edges
	 Disable moment transfer on bar ends if you want simply supported behaviour.	 Disable moment transfer on bar ends if you want simply supported behaviour.
	 <ul style="list-style-type: none"> <li>• Easy modelling</li> <li>• Border effects</li> </ul>	 <ul style="list-style-type: none"> <li>• Complex modelling</li> <li>• Border effects</li> <li>• High risk of instabilities</li> </ul>
	Reinforcement in plates and beam should be placed.	Reinforcement in plates and beam should be placed.

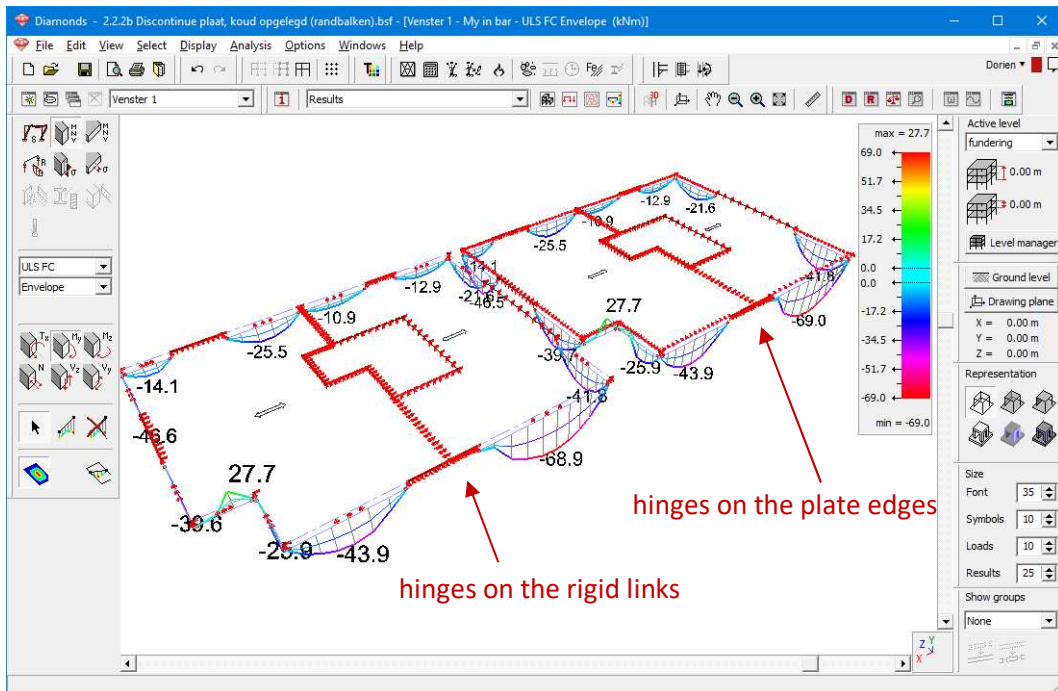


Result:

- The bending moment in the field is indeed comparable.
- Both models now contain retaining moments. Although the hinges prevent the transmission of internal forces between the plates and the beam, the plate itself remains bearing in two directions. So here, it is the compatibility of the deformations that causes the retaining moments.





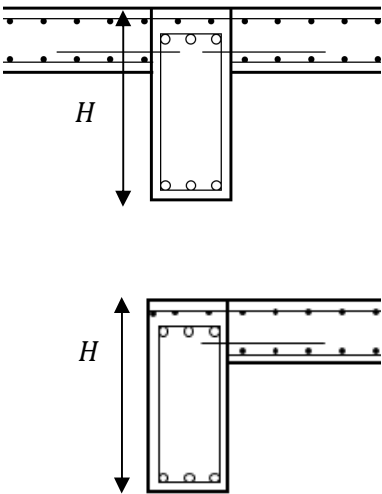
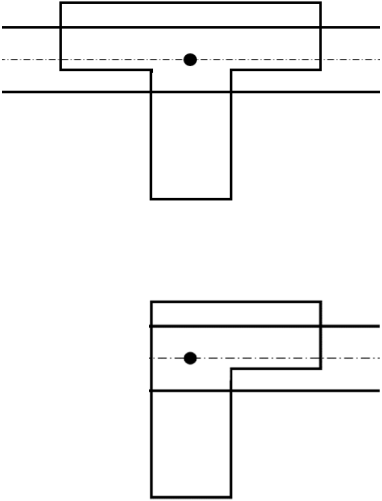
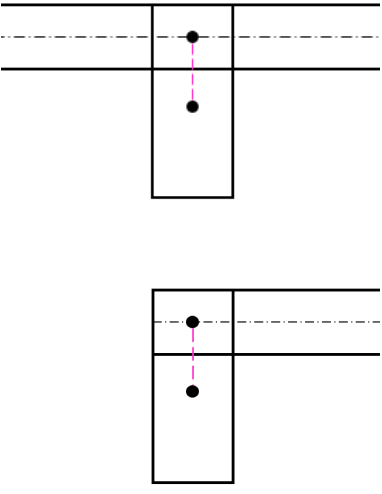




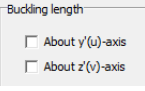
Note: for beams along the edge of a plate, it doesn't matter if you apply the hinges on the border of the plate or on the rigid links. Both give similar results.



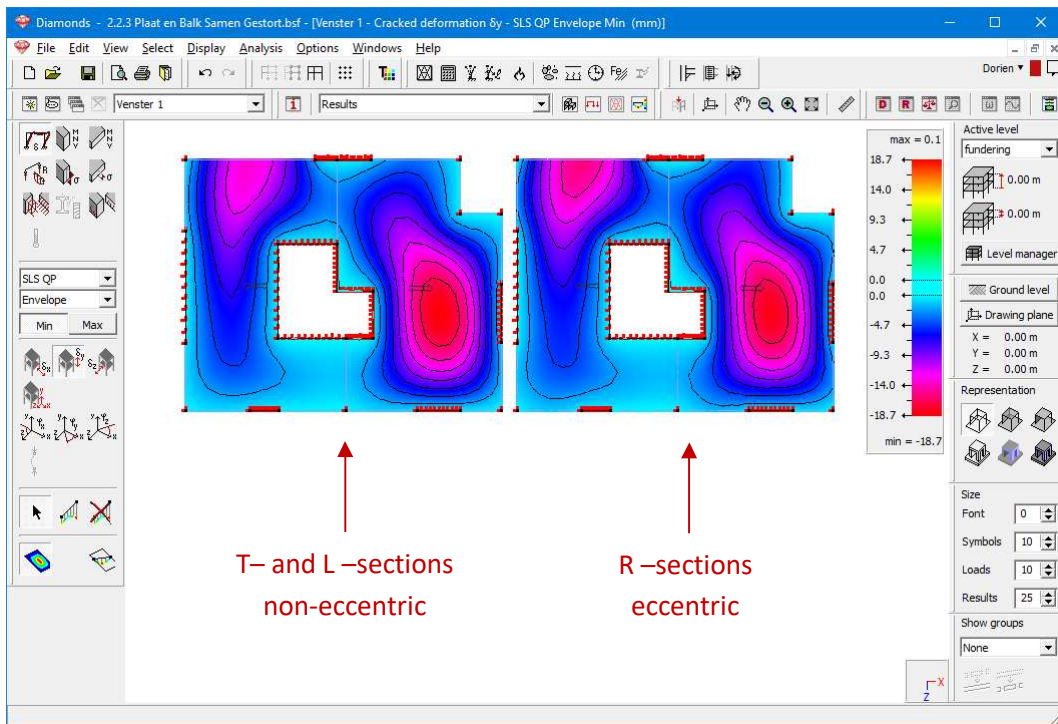
### 3.2.4. Case 3: beam and plate poured together

The plates in the 2D plate model are poured together with the central and edge beams. Both beam and plate will work together as a whole.

The table below lists the assumptions made for each model.

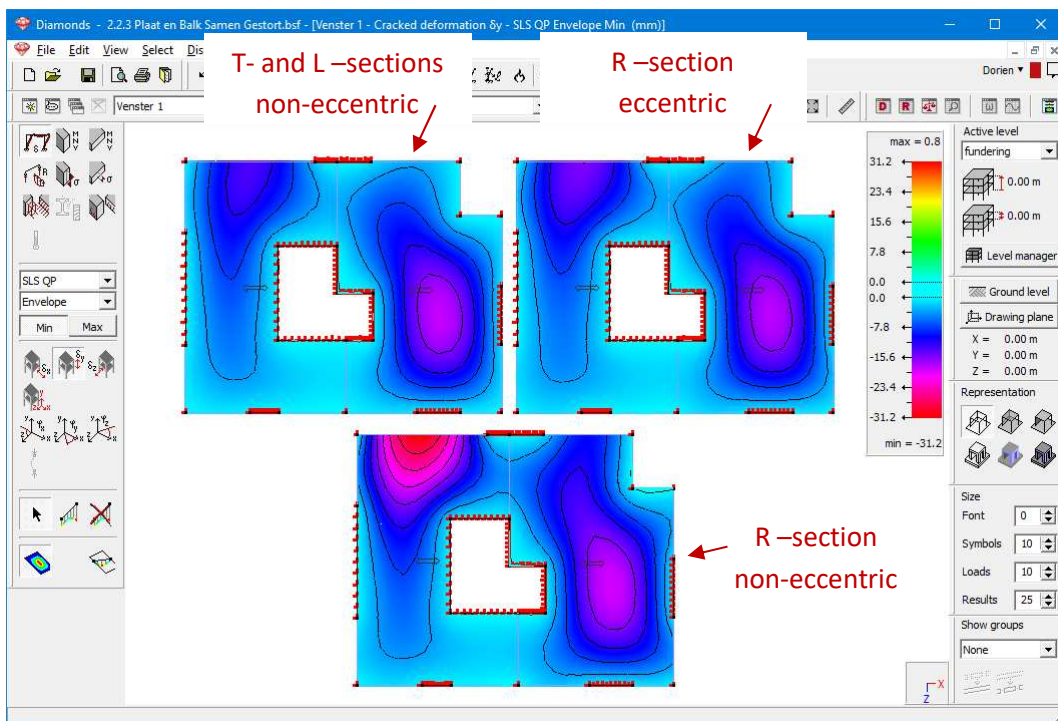
REALITY	DIAMONDS	
	WITHOUT ECCENTRICITIES  License 2D slabs required	WITH ECCENTRICITIES  License 2D slabs + 2D plates required
<p>Case 3: Beam and plate poured together</p> 		 <p> Top beam = top plate</p>
	 <ul style="list-style-type: none"> <li>• Beam = T or L-section with total height <math>H</math>. An R-section would underestimate the stiffness.</li> <li>• Effective width determined using EN 1992-1-1 §5.3.2.1.</li> </ul>	 Beam height = $H$
	<p><b>!</b></p> <ul style="list-style-type: none"> <li>• Easy modelling (more additional work to calculate the effective widths)</li> <li>• Bending moment can still be transferred from the plates to the beam. This will give torsion in the beams. Setting the torsional stiffness <math>I_t</math> of the beams to a small value, will eliminate the torsion, but with the risk of large (angular) deformation.</li> <li>• Higher self-weight because of double section, but compensated by larger compression zone.</li> </ul>	<p><b>!</b></p> <ul style="list-style-type: none"> <li>• Easy modelling</li> <li>• Axial forces will occur in beams and plates! Turn off the buckling check in eccentric beams ( &gt; uncheck the checkboxes before the buckling lengths ).</li> </ul>
	Reinforcement in plates and beam should be placed.	Reinforcement in plates and beam should be placed.

In this modelling, it hard to compare the internal forces. Both models do not have the same self-weight and axial forces will occur in the eccentricity model. So, the cracked deformation (+ creep + extend theory to axial forces) is used to compare the stiffness between the two models.



In the image above we see that the 2 modelling approaches (with or without eccentricities) give similar results, yet not entirely the same. This is because it is hard to estimate/calculate the effective widths of the T- and L-sections.

Out of curiosity, let's add a model in which non-eccentric R-sections are used. While we had a maximum cracked deformation after creep of 18,7mm (see previous image), we now find a maximum of 31,2mm. Confirming the statement that using a non-eccentric R-section to simulate beam-plate poured together will underestimate the stiffness of the beams.

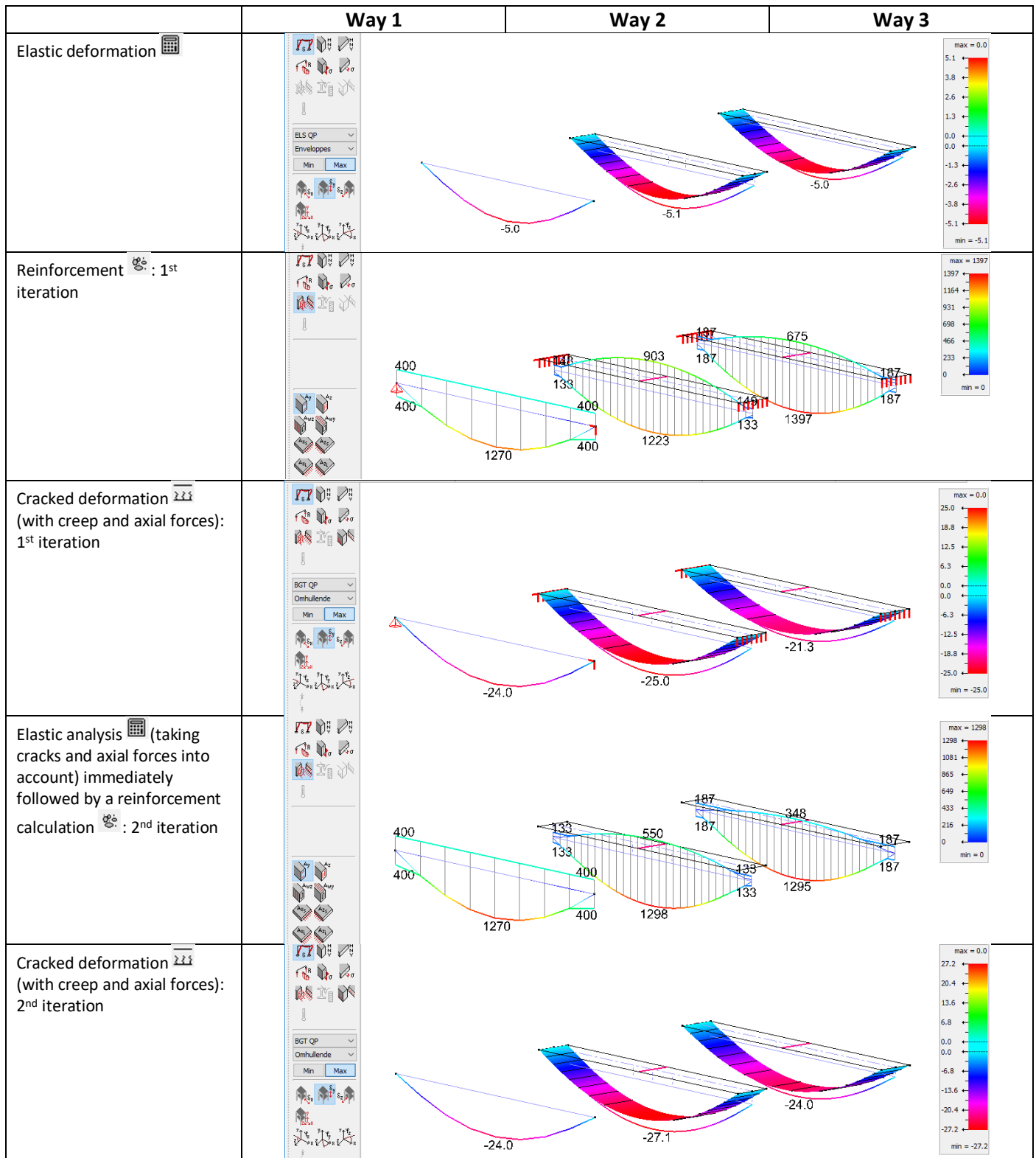


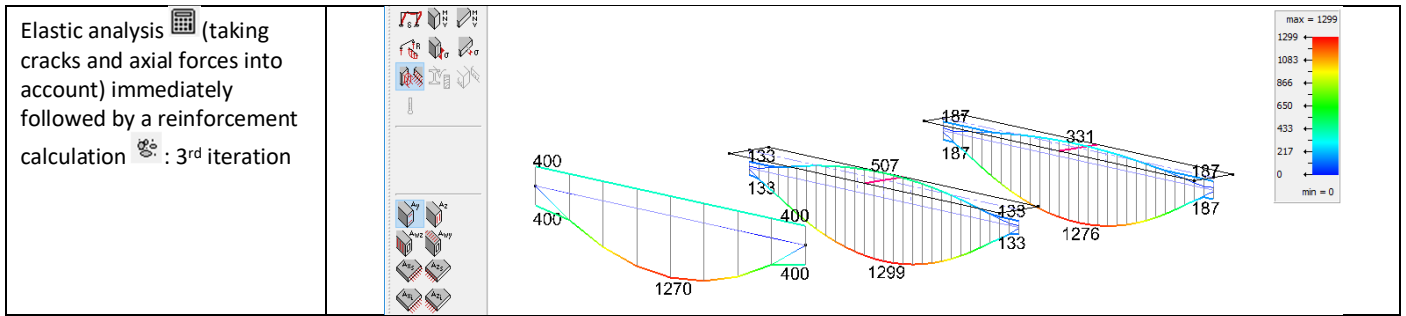
### 3.2.4.1. Why Upper side beam = upper side plate for Case 3?

In case 3 *upper side beam = upper side plate* was chosen. As a result, the plate thickness must be added to the beam height, resulting in additional self-weight. Something that we (understandably) experience as contradictory. But that extra beam height is necessary to develop sufficient stiffness. We again include the beam models from §2.1:

- Way 1 from §2.1 corresponds to Case 3 modelled without eccentricities.
- Way 3 from §2.1 corresponds to Case 3 modelled with eccentricities  
(= plate thickness added to beam height = the modelling that feels a bit contradictory)
- Way 2 from §2.1 corresponds to Case 3 with eccentricities  
(= plate thickness NOT added to beam height = the modelling we would expect at first glance)

The purpose of Diamonds is to design, therefore we focus on the reinforcement and cracked deformation. We will recalculate the model multiple times and look at how the reinforcement amounts and cracked deformation evolves in the 3 different models:

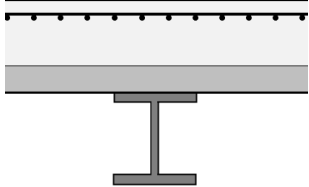
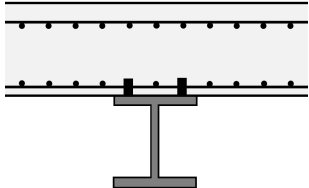





Conclusion: Way 1 and 3 match the best when it comes to the cracked deformation and reinforcement amount. Way 2 comes close, but is slightly less stiff, resulting in greater deflections and more reinforcement.


## 4. Collaboration steel beam – concrete plate


Analogous to concrete, in this section we consider two cases which a steel beam is poured into a concrete plate.

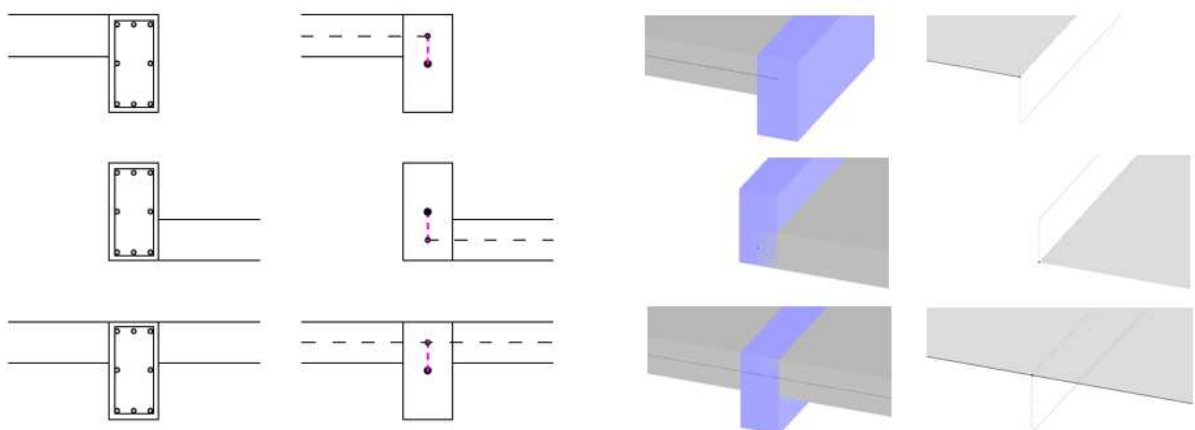
REALITY	DIAMONDS
<p>Case 4: préslabs simply supported by a steel beam</p> 	<p>See §3.2.1</p>
<p>Case 5: steel beam connected to a concrete plate using dowels</p> 	<p>See §3.2.4</p> <p>Set  <i>bottom surface plate = top surface beam.</i></p>

## 5. Non-standard eccentricities

Diamonds creates eccentricities by using rigid links. Rigid links are infinitely stiff elements, which do not have a cross-section or material. Their purpose is to transfer forces between elements.


If you set beam eccentric with the button , Diamonds will automatically generate the rigid links. The alignment (top surface beam = top surface plate, ...) determines the length of the rigid link.

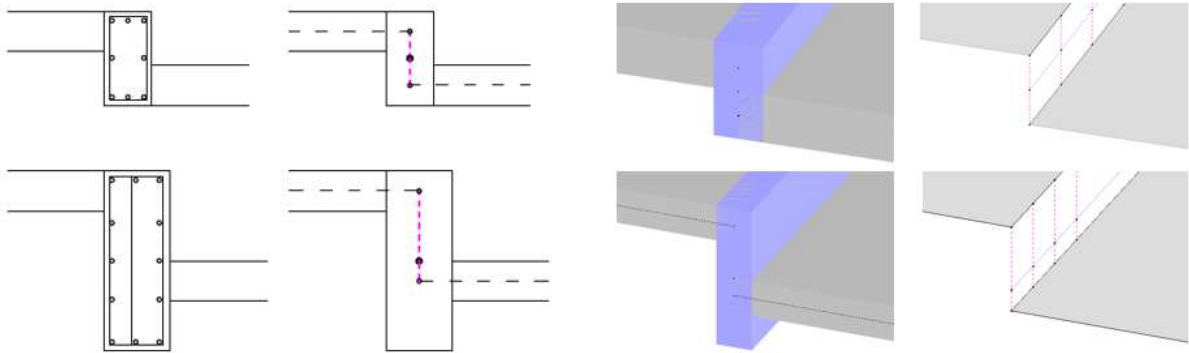
The images below show standard cases. In the images, the rigid link is represented as a pink bar. In Diamonds, a rigid link generated by using the button , is represented by a dotted line in the same colour as the beam.



For non-standard eccentricities like the examples below, you manually have to add the rigid link. This is done like this:

- Draw the elements (plate(s) and beam) on the correct level (Y-coordinate). Use the plate and beam axis to determine these levels. The difference in level determines the length of the rigid links.

- At the locations of the rigid links: draw a line, select the line and click on . The black continuous line you selected will be a dashed pink line now.
- The torsion effect is in the rigid links and will go to waste.
- This type of modelling is only advised for smaller models, not for large 3D projects.



Note: if plates are in different levels, you'll need a 2D Plates + 3D Plates license!